

# Lecture 15

- curves, vector fields
- line integral of the second kind

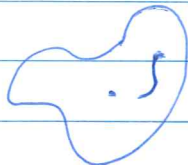
First let's review some definitions.

A region is always the set of points bounded by one or several piecewise  $C^1$ -curves in  $\mathbb{R}^2$ . A region is the set of points bdd by one or several piecewise  $C^1$ -surfaces in  $\mathbb{R}^3$ . It is possible to remove some points in a 2-D or 3-D region,



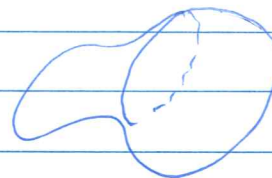
bdd by 2 curves

$$n=2$$

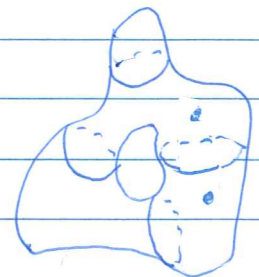


bdd by one curve  
one pt and one  
curve removed.

$$n=2$$



$$n=3$$



2 points are  
removed  
 $n=3$

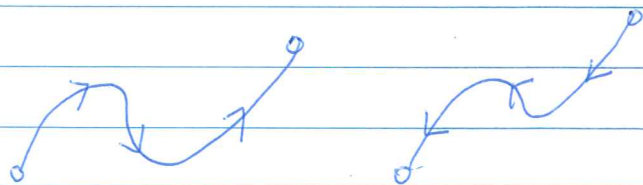
A region consists of interior pts and boundary pts. It is always bdd.



A parametric curve is a continuous map  $\gamma: [a, b] \rightarrow \mathbb{R}^2, \mathbb{R}^3$ . A regular parametric curve  $\gamma: [a, b] \rightarrow \mathbb{R}^2, \mathbb{R}^3$  satisfies  $\gamma'(t)$  contin.,  $\forall t$  and  $|\gamma'(t)| > 0$ . A piecewise regular parametric curve  $\gamma: [a, b] \rightarrow \mathbb{R}^2, \mathbb{R}^3$  is a parametric curve so that its restriction on  $[a, t_1], [t_1, t_2], \dots, [t_{n-1}, b]$  are regular.

A (geometric) curve  $C$  is a subset in  $\mathbb{R}^2, \mathbb{R}^3$  such that  $\exists$  a parametric curve  $\gamma: [a, b] \rightarrow C$  which is regular, and bijective  $[a, b]$ . Such <sup>parametric</sup> curve is called a parametrization of  $C$ . Any parametrization of  $C$  carries an orientation on  $C$ . When  $\gamma: [a, b] \rightarrow C$ , the new parametrization  $\eta: [a, b] \rightarrow C$  given by  $\eta(t) = \gamma(a+b-t)$ .

$\eta(a) = \gamma(b)$ ,  $\eta(b) = \gamma(a)$ , reverse the orientation. One can show that there are exactly two possible orientations on a curve  $C$ . More precisely, let  $\gamma_1$  and  $\gamma_2$  be two parametrizations of the same  $C$  on  $[a, b]$  and  $[c, d]$  respectively. Then  $\exists \varphi: [a, b] \rightarrow [c, d]$   $C^1$ -bijection such that  $\gamma_2(\varphi(t)) = \gamma_1(t)$ ,  $t \in [a, b]$ , or  $\gamma_2(\varphi(t)) = \gamma_1(a+b-t)$ .



Only 2 orientations on the same  $C$ .

When  $C$  represents an oriented curve (a curve with an orientation) we denote its reverse oriented curve by  $-C$ .

The tangent of a parametric curve  $\gamma$  is given by  $\gamma'(t)$ . Its magnitude and direction are given respectively by

$$|\gamma'(t)| = (x'^2(t) + y'^2(t))^{1/2} \quad n=2,$$

$$= (x'^2(t) + y'^2(t) + z'^2(t))^{1/2} \quad n=3,$$

and

$$\frac{\gamma'(t)}{|\gamma'(t)|}.$$

When  $C$  is an oriented <sup>curve</sup> parametrized by  $\gamma$ , its unit tangent at  $\gamma(t)$  is  $\frac{\gamma'(t)}{|\gamma'(t)|}$ .

We use notation

$$\vec{T}(\gamma(t)) \quad \text{or} \quad \hat{t}(\gamma(t))$$

to denote it. Clearly, it is indep of the parametrization, i.e.

$$\gamma_1: [a, b] \rightarrow \mathbb{R}^2, \mathbb{R}^3$$

$\gamma_2: [c, d] \rightarrow \mathbb{R}^2, \mathbb{R}^3$ . Two parametrizations with the same orientation.

Then  $\gamma_2(\varphi(t)) = \gamma_1(t)$  for  $\varphi: [a, b] \rightarrow [c, d]$   $C^1$ -bijection, since  $\varphi(a) = c$ ,  $\varphi(b) = d$ ,  $\varphi'(t) > 0$ . thus

$$\gamma_1'(t) = \gamma_2'(z) \varphi'(t), \quad z = \varphi(t)$$

$$\therefore \frac{\gamma_1'(t)}{|\gamma_1'(t)|} = \frac{\gamma_2'(z) \varphi'(t)}{|\gamma_2'(z)|}$$

$$= \frac{\gamma_2'(z) \varphi'(t)}{|\gamma_2'(z)| |\varphi'(t)|} \quad (\varphi'(t) = |\varphi'(t)| \because \varphi' > 0)$$

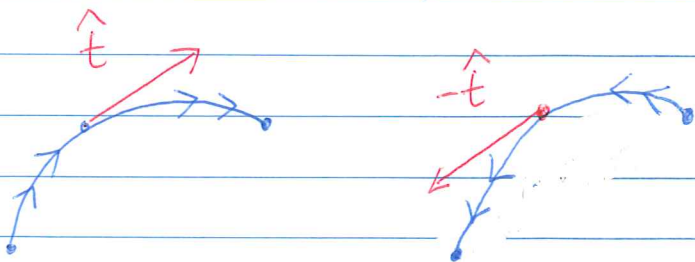
$$= \frac{\gamma_2'(z)}{|\gamma_2'(z)|}$$

On the other hand, the unit tangent of  $-C$  is the negative of the unit tangent of  $C$  at the same point. Let  $p = \gamma_2(t) = \gamma_1(a+b-t)$  be the same pt on  $C$ .

$$\gamma_2'(t) = -\gamma_1'(a+b-t)$$

$$\therefore \frac{\gamma_2'(t)}{|\gamma_2'(t)|} = -\frac{\gamma_1'(a+b-t)}{|\gamma_1'(a+b-t)|}$$

$\uparrow$  the unit tg of  $-C$  at  $\gamma_2(t)$ 
 $\leftarrow$  the unit tg of  $C$  at  $\gamma_1(a+b-t)$ .



The pt on curve is  $\gamma_2(t) = \gamma_1(a+b-t)$

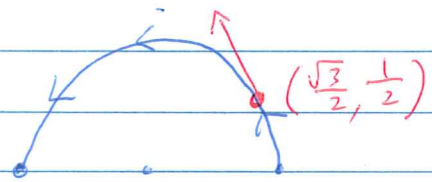
eg 1 Consider the following two parametrizations for the oriented semicircle (anti-clockwise).

$$\gamma_1: [0, \pi] \rightarrow (\cos t, \sin t)$$

$$\gamma_2: [-1, 1] \rightarrow (-t, \sqrt{1-t^2})$$

Let's find out its unit tg at the pt  $(\frac{\sqrt{3}}{2}, \frac{1}{2})$  i.e.  $\gamma_1(\frac{\pi}{6})$

or  $\gamma_2(-\frac{\sqrt{3}}{2})$



Use  $\gamma_1$ :  $\gamma_1'(t) = (-\sin t, \cos t)$ ,  $|\gamma_1'(t)| = \sqrt{(-\sin t)^2 + \cos^2 t} = 1$ ,

$$\therefore \frac{\gamma_1'(t)}{|\gamma_1'(t)|} = \frac{(-\sin t, \cos t)}{1} = \left(-\frac{1}{2}, \frac{\sqrt{3}}{2}\right) \text{ at } t = \frac{\pi}{6}$$

Use  $\gamma_2$ :  $\gamma_2'(t) = \left(-1, \frac{-t}{\sqrt{1-t^2}}\right)$ ,  $|\gamma_2'(t)| = \left(1 + \frac{t^2}{1-t^2}\right)^{\frac{1}{2}} = \frac{1}{\sqrt{1-t^2}}$ .

$$\frac{\gamma_2'(t)}{|\gamma_2'(t)|} = \sqrt{1-t^2} \left(-1, \frac{-t}{\sqrt{1-t^2}}\right) = \left(-\frac{1}{2}, \frac{\sqrt{3}}{2}\right) \text{ at } t = -\frac{\sqrt{3}}{2}$$

$\therefore \hat{t}$ , or  $\vec{T}$  are the same at  $(\frac{\sqrt{3}}{2}, \frac{1}{2})$  on  $C$ .

x                      x                      x

Vector fields on a region in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  are

$$\vec{F}(x, y) = (P(x, y), Q(x, y)) \text{ or}$$

$$= (P(x, y, z), Q(x, y, z), R(x, y, z))$$

Let  $C_1$  be a curve with parametrization  $\gamma: [a, b]$  and  
 and  $C_2$  another curve with parametrization  $\eta: [c, d]$ . When  
 $\gamma(b) = \eta(c)$ , one can put  $C_1$  and  $C_2$  together to form a  
 new curve  $C$ . It is continuous at  $\gamma(b)$  ( $\because \gamma(b) = \eta(c)$ ) but  
 may not be differentiable there (unless  $\gamma'(b) = \eta'(c)$ ), It is  
 only piecewise regular even when  $\gamma$  and  $\eta$  are regular.

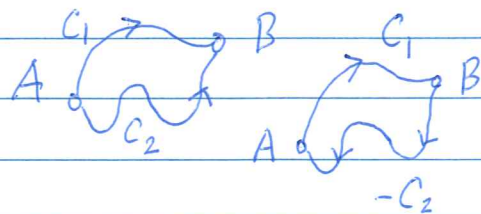
We can also form a new parametrization of  $C$ ,  $\tilde{\gamma}$ , on a  
 single interval, but this is not always necessary.

Usually we denote  $C$  by  $C_1 + C_2$ . Similarly, one defines

$$C_1 + C_2 + \dots + C_n.$$

We also define  $C_1 - C_2 = C_1 + (-C_2)$ .

Let  $C_i$ ,  $i=1, 2$ , be two curves from  $A$  to  $B$  ( $A, B \in \mathbb{R}^2, \mathbb{R}^3$ ),  
 then  $C_1 - C_2$  forms a closed curve.



x                      x                      x

A vector field in a region (or on the interior of a region)

$$\vec{F}(x, y) = (P(x, y), Q(x, y)) \quad m=2$$

$$\vec{F}(x, y, z) = (P(x, y, z), Q(x, y, z), R(x, y, z)), \quad n=3$$

$\vec{F}$  is conti/ $C^1$  whenever its components are conti/ $C^1$ .

Some examples of vector fields were given in the last lectures.

Here let's single out a class of special, but important vector fields.

$\vec{F}$

A vector field  $\vec{F}$  is called a gradient vector field if

$\exists$  function  $\Phi$  in  $D$  such that

$$\begin{aligned}\vec{F} &= \nabla \Phi = \left( \frac{\partial \Phi}{\partial x}, \frac{\partial \Phi}{\partial y} \right) \text{ or} \\ &= \left( \frac{\partial \Phi}{\partial x}, \frac{\partial \Phi}{\partial y}, \frac{\partial \Phi}{\partial z} \right).\end{aligned}$$

$\Phi$  is called the potential of  $\vec{F}$ . It is unique up to the addition of an arbitrary constant.

A vector field in general depends on 2 unknowns  $P, Q$  ( $n=2$ ) and 3 unknowns  $P, Q, R$  ( $n=3$ ). But a gradient v.f. only depends on a single unknown  $\Phi$ , so it is very special. On the other hand, it is important because some basic v.f. in physics are gradient v.f.

e.g. 2 Any constant v.f. is gradient.

Let  $\vec{F}(x, y, z) = (a, b, c)$  be constant v.f. then

$\Phi(x, y, z) = ax + by + cz$  is its potential.

e.g. 3 The gravitational v.f.

$$\vec{F} = -\frac{mMG}{r^3} \vec{r}, \quad \vec{r} = (x, y, z)$$

is a gradient v.f. For, let

$$\Phi(x, y, z) = \frac{mMG}{|r|} = \frac{mMG}{(x^2 + y^2 + z^2)^{1/2}}$$

Then, by a direct check,

$$\frac{\partial \Phi}{\partial x}(x, y, z) = -\frac{mMG}{r^3} x,$$

$$\frac{\partial \Phi}{\partial y}(x, y, z) = -\frac{mMG}{r^3} y,$$

$$\frac{\partial \Phi}{\partial z}(x, y, z) = -\frac{mMG}{r^3} z, \text{ so}$$

$$\nabla \Phi = \vec{F}.$$

x x x

Now, we come to define the line integral of a v.f.  $\vec{F}$  along an oriented curve  $C$ .

First, recall that for a function defined along  $C$ , its line integral is

$$\int_C f ds = \lim_{\|P\| \rightarrow 0} \sum_j f(\gamma(t_j^*)) |\gamma(t_j) - \gamma(t_{j-1})|,$$

where  $\gamma$  is a parametrization of  $C$ . This integral exists when  $f$  is continuous along  $C$ . Moreover, it is independent of the orientation induced by  $\gamma$ .

Now, given an oriented curve  $C$  and a v.f. along  $C$ , the line integral of the vector field  $\vec{F}$  along  $C$  is defined to be

$$\int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \vec{T} ds \quad (1)$$

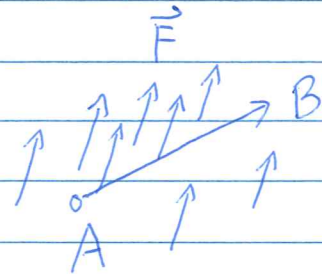
where  $\vec{T} = \gamma'(t) / \|\gamma'(t)\|$  the unit tangent of a parametrization  $\gamma$  which fits in the orientation of  $C$ . Note that  $\vec{T}$  is independent of the choice of  $\gamma$ . However, when the orientation of  $C$  is reversed,  $\vec{T}$  goes over to  $-\vec{T}$ , so we have

$$\int_{-C} \vec{F} \cdot d\vec{r} = - \int_C \vec{F} \cdot d\vec{r}.$$

where  $C = C_1 + \dots + C_n$ ,  $C_j$   $C$ -curve, define  $\int_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \dots + \int_{C_n} \vec{F} \cdot d\vec{r}$ .

The motivation in the definition in (1) arises from physics. In mechanics, a particle moves from point  $A$  to point  $B$  under a constant force field along  $\vec{AB}$ ,

the work done of  $\vec{F}$  on this particle is given by  $\vec{F} \cdot \vec{v}$



where  $\vec{v}$  is the vector from  $A$  to  $B$ . Now, the work done of the particle along a curve  $C$  under a general force field

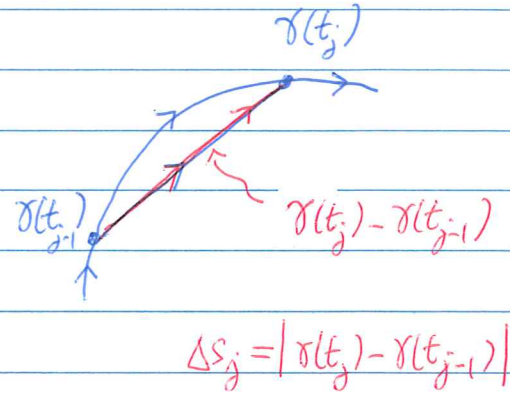
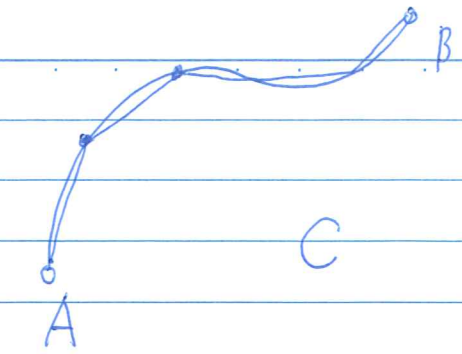


can be defined via Riemann sums,

$$\int_C \vec{F} \cdot d\vec{r}$$

$$\sim \sum_j \vec{F}(\gamma(t_j^*)) \cdot (\vec{\gamma}(t_j) - \vec{\gamma}(t_{j-1}))$$

$$= \sum_j \vec{F}(\gamma(t_j^*)) \cdot \frac{\vec{\gamma}(t_j) - \vec{\gamma}(t_{j-1})}{|\vec{\gamma}(t_j) - \vec{\gamma}(t_{j-1})|} \Delta s_j$$



$$\rightarrow \int_C \vec{F} \cdot \vec{T} ds \quad \text{as } \|P\| \rightarrow 0.$$

Another formula of the line integral can be obtained by

$$\sum_j \vec{F}(\gamma(t_j^*)) \cdot (\vec{\gamma}(t_j) - \vec{\gamma}(t_{j-1}))$$

$$= \sum_j [P(\gamma(t_j^*)) (x(t_j) - x(t_{j-1})) + Q(\gamma(t_j^*)) (y(t_j) - y(t_{j-1}))]$$

$$= \sum_j (P(\gamma(t_j^*)) x'(t_j^*) + Q(\gamma(t_j^*)) y'(t_j^*)) (t_j - t_{j-1})$$

$$\rightarrow \int_C (P(\gamma(t)) x'(t) + Q(\gamma(t)) y'(t)) dt$$

when  $\vec{F} = (P, Q)$ ,  $\gamma(t) = (x(t), y(t))$ .

therefore,

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b (P(x(t))x'(t) + Q(x(t))y'(t)) dt \quad (n=2)$$

$$= \int_a^b (P(x(t))x'(t) + Q(x(t))y'(t) + R(x(t))z'(t)) dt \quad (n=3)$$

This is the most common way to evaluate the integral. It also motivates the new notations

$$\int_C P dx + Q dy, \quad \int_C P dx + Q dy + R dz.$$

e.g 4. Evaluate  $\int_C \vec{F} \cdot d\vec{r}$  where

$$C: \gamma: [0, \frac{\pi}{2}] \rightarrow (\cos t, \sin t, t)$$

$$\vec{F}(x, y, z) = (x, xy, z^3)$$

$$\gamma'(t) = (x'(t), y'(t), z'(t)) = (-\sin t, \cos t, 1)$$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C P dx + Q dy + R dz = \int_C x dx + xy dy + z^3 dz \\ &= \int_0^{\frac{\pi}{2}} \cos t (-\sin t) dt + \int_0^{\frac{\pi}{2}} \cos t \sin t \cos t dt \\ &\quad + \int_0^{\frac{\pi}{2}} t^3 \cdot 1 dt \end{aligned}$$

$$= \int_0^{\frac{\pi}{2}} -\cos t \sin t dt + \int_0^{\frac{\pi}{2}} \sin t \cos^2 t dt + \int_0^{\frac{\pi}{2}} t^3 dt$$

$$= -\frac{1}{2} + \frac{1}{3} + \frac{\pi^4}{64} = \frac{1}{6} + \frac{\pi^4}{64} \quad \#$$

Although the line integral of the second kind, that is, the line integral of a v.f. along an oriented curve, is motivated from work done, it has applications elsewhere.

Let  $C$  be a closed curve in  $\mathbb{R}^2, \mathbb{R}^3$  and  $\vec{u}$  a vector field on the region containing  $C$ . The line integral

$$\int_C \vec{u} \cdot d\vec{r}$$

is called the circulation of  $\vec{u}$  around  $C$ . When  $\vec{u}$  is the velocity of a fluid,  $\vec{u} \cdot \vec{T}$  measures the amount of fluid moves along the curve  $C$  in unit time, hence the line integral measure the total amount of the fluid goes around the curve.

When  $n=2$ , let  $\gamma$  parametrize  $C$ .

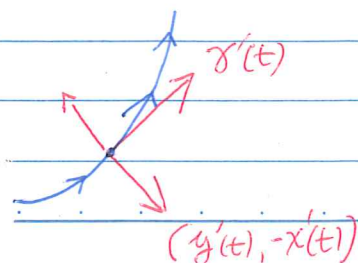
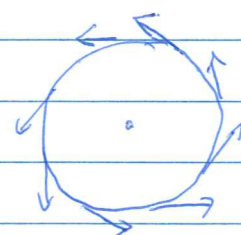
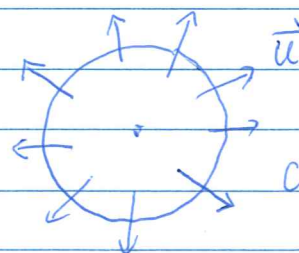
$$\gamma(t) = (x(t), y(t))$$

$$\gamma'(t) = (x'(t), y'(t))$$

The vectors  $(-y'(t), x'(t))$ ,  $(y'(t), -x'(t))$  satisfy

$$(-y'(t), x'(t)) \cdot \gamma'(t) = 0$$

Use  $\hat{n} = \frac{(-y'(t), x'(t))}{|\gamma'(t)|}$  or  $\frac{(y'(t), -x'(t))}{|\gamma'(t)|}$

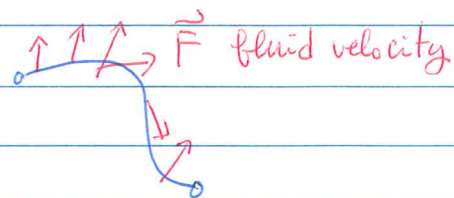


to denote the normal direction.

Let  $C$  be a curve in  $\mathbb{R}^2$  (not nec. closed) with a choice of unit normal  $\hat{n}$ , the flux of the vector field  $\vec{F}$  across  $C$  along  $\hat{n}$  is defined to be

$$\int_C \vec{F} \cdot \hat{n} \, ds.$$

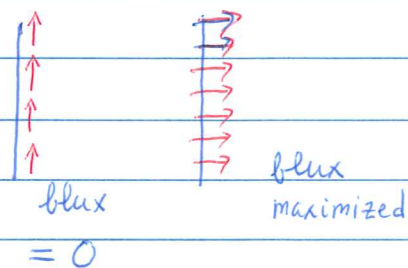
It measures the amount of fluid passing through  $C$  in unit time.



e.g.5 Consider the v.f.

$$(ax+by, cx+dy), \quad a^2+b^2=1 \\ c^2+d^2=1$$

on the circle (ant-clockwise)



$$t \mapsto (\cos t, \sin t)$$

Find the circulation and flux of the v.f. along / across the circle.

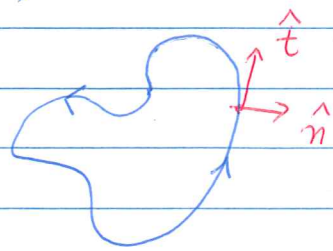
$$\gamma(t) = (\cos t, \sin t),$$

$$\hat{t} = (-\sin t, \cos t)$$

$$\hat{n} = (\cos t, \sin t) \quad (\text{for a closed curve, take } \hat{n} \text{ to be the outer one})$$

circulation =

$$\int_C \vec{F} \cdot \hat{t} \, ds = \int_0^{2\pi} (a \cos t + b \sin t, c \cos t + d \sin t) \cdot (-\sin t, \cos t) \, dt$$



$$= \int_0^{2\pi} (a \cos t (-\sin t) + b \sin t (-\sin t) + c \cos^2 t + d \sin t \cos t) dt$$

$$= (-b+c) \pi$$

therefore, the circulation is maximal when  $a=0, b=-1, c=1$  and  $d=0$ . that is, the v.f. is  $(-\sin t, \cos t)$ . It is minimal at  $b=1$  and  $c=-1$  ( $a=d=0$ ), i.e., v.f. is  $(\sin t, -\cos t)$ .

The flux

$$\int_C \vec{F} \cdot \hat{n} ds = \int_0^{2\pi} (a \cos t + b \sin t, c \cos t + d \sin t) \cdot (\cos t, \sin t) dt$$

$$= (a+d) \pi$$

So, the flux is maximal when v.f.  $(\cos t, \sin t)$  ( $a=d=1, b=c=0$ ) and minimal when v.f.  $(-\cos t, -\sin t)$  ( $a=d=-1, b=c=0$ ).